

## 安装 / ASSEMBLY:

**01** 将左右垂尾涂上EPP胶水，分别安装入机背上相应的插槽内，调整好角度固定。

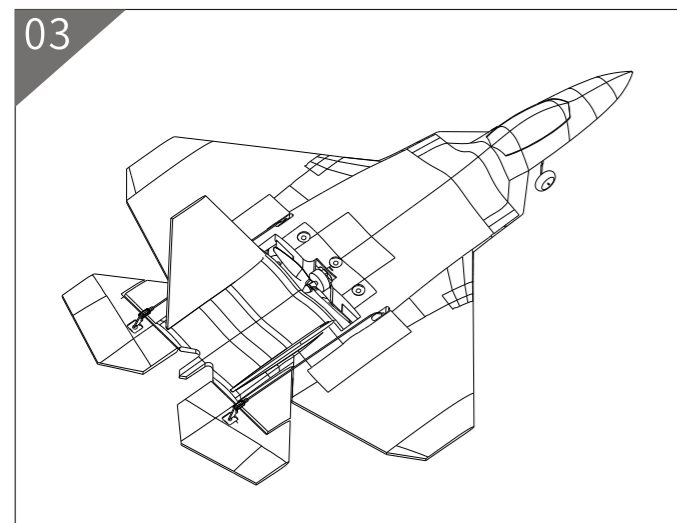
EPP Glue

垂尾角度参考

To glue the EPP to the left and right vertical tail, and separate install them into the corresponding slot of the back of the airframe, and adjust the angle and then fix it.

**02** 将起落架插机腹上的起落架插槽内。

Insert the landing gear into the landing gear slot of the aircraft belly.



**特别提醒**  
SPECIAL REMINDER

建议电池固定位置  
Suggested Battery Fixed Position

105±5mm  
CG重心

## 配置包装清单 / CONFIGURATION BOX CONTENTS:

使用本产品之前，请检查产品包装内是否包含以下所有物品。若有缺失，请与销售方联系。  
Before using the product, please check the package and see if it contains all of the items.  
If there is any defects, please contact with the seller.

机体(已预装电机、舵机、电调、接收机 <带陀螺仪功能>、螺旋桨)×1  
Fuselage (Pre-installed motor, steering gear, electrical regulation, receiver <with gyroscope function>, propeller) ×1

左垂尾×1  
Left vertical tail×1

右垂尾×1  
Right vertical tail×1

起落架(选配另购)×1  
Landing gear (selection)×1

锂电池(7.4V,JST头)×1  
Li-Po Battery(7.4V,JST)×1

锂电平衡充×1  
Balanced charger×1

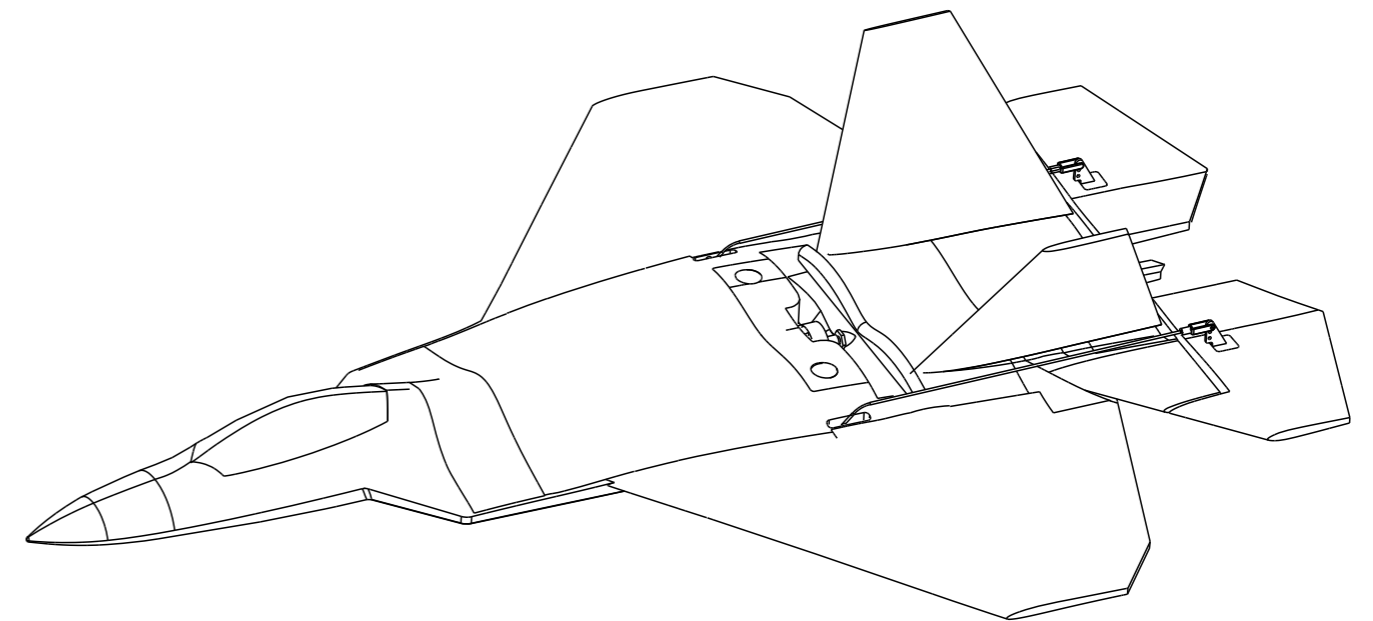
充电器适配线×1  
Charger adapter ×1

遥控器×1  
Transmitter×1

说明书×1  
Manual×1

# Mini Parkflyer F22-580 Electric R/C Model Aircraft 迷你简易电动遥控模型飞机

## 快速组装说明 QUICK ASSEMBLE MANUAL



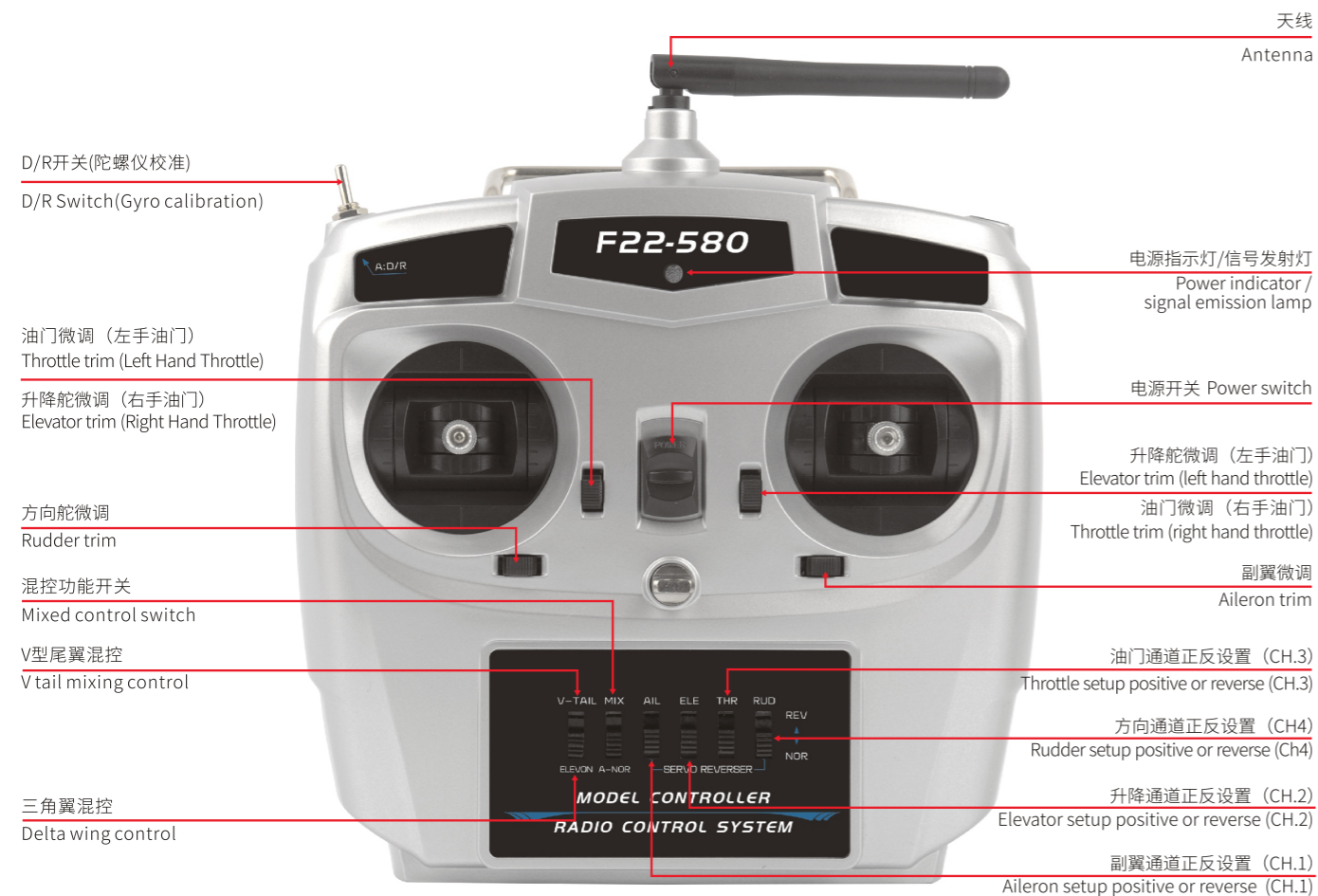
Spe.规格	
Wingspan/翼展	580 mm / 22.83 in
length/机长	817mm / 32.16 in
Flight weight/飞行重量	350g / 12.34 oz (2s)
Cruising speed/巡航速度	50km/h
Flight Time/飞行时间	about 10-15 Minute
Main material/主材质	EPP
Aileron/副翼	N/A 无
Horizontal Tail/平尾	Yes 有
Vertical tail/垂尾	Yes 有
Suitable for experience level 适合经验水平	Zero or primary/零有或初级
Difficulty of assembly 组装难度	5 Minute
Suggested manipulation age 建议操控年龄	14 or above/14周岁或以上
Working environment temperature 工作环境温度	0°C~40°C

Con./配置	KIT	PNP	RTF
Motor/电机	—	—	2204-2600 kV brushless/ 无刷
Servo/舵机	—	—	9g simulate servo/模拟舵机×2
Battery/电池	—	—	7.4V,1200mAh,25C/锂电
ESC/电调	—	—	20A brushless/无刷
Propeller/桨叶	—	—	6045 2 blsde/两叶桨
Landing gear/起落架	—	—	Steel wire landing gear(selection) 插拔式钢丝固定起落架(选配另购)
Take off mode/起飞模式	—	—	Sliding, Hand tossing 滑跑起飞、手抛起飞
Flight distance/飞行距离	—	—	500 m
Transmitter/遥控器	—	—	4 Channel , receiver with gyro 4 通遥控器,接收机带陀螺仪
Charger/充电器	—	—	2s balance charge/2S 平衡充电器

产品序列号:

# 4通道2.4GHz遥控器使用说明

## 4CH2.4GHzRADIO CONTROL SYSTEM INSTRUCTIONS



### 一. 遥控器基本参数:

1. 适合使用于: 固定翼模型飞机、车、船
2. 发射功率: 小于或等于 100 mW
3. 发射频率: 2.4 GHz
4. 地面控制范围: 大于 500 米
5. 发射机供电要求: DC+4.5V~15V (4 节 5号/AAA 电池)
6. 接收机供电要求: DC+5V

### 二. 注意事项:

1. 确保电池提供足够的电力。当 哔 哔 报警声音和红色电源指示灯闪烁, 请更换遥控器电池。
2. 在结束玩模型的时候, 先把油门拉到底, 再关闭遥控器。

### 1. Basic parameters of remote control:

1. Suitable for: fixed wing aircraft, vehicles, ships
2. Transmit power: less than or equal to 100 mW
3. Transmission frequency: 2.4 GHz
4. Ground control range: more than 500 meters
5. Transmitter power supply requirements: DC+4.5V ~ 15V (4 AAA batteries)
6. Receiver require power supply: DC+6V

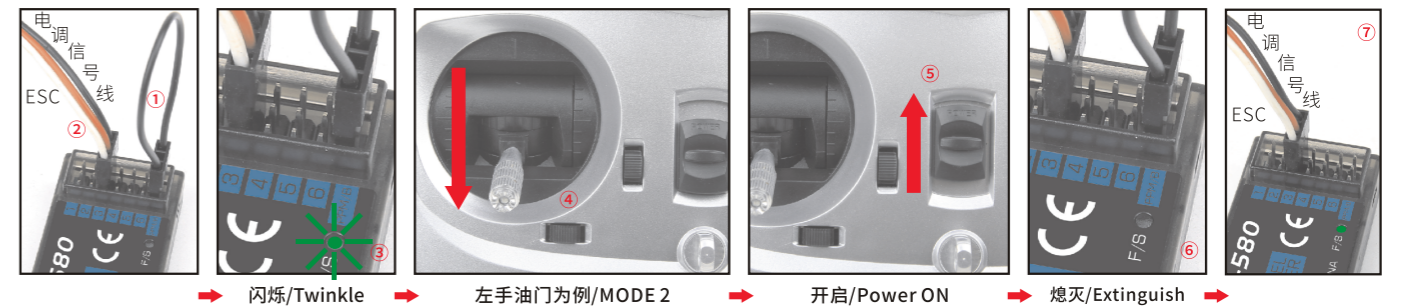
### 2. Attentions:

1. Make sure the battery to provide enough power. When there is a breakdown sound wow and red power indicator lights, please replace the remote control battery.
2. At the end of the flight, pull the throttle to the bottom, and then turn off the remote control.

### 三. 遥控器和接收机对码的操作步骤:

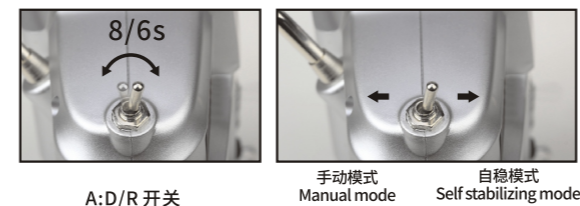
1. 关闭发射机。
2. 把黑色“对码线”插头插在接收机“B”的接口, 然后把电调的信号线插在接收机第三通道口通电。
3. 接收将有一个持续闪烁的LED绿灯。
4. 将遥控器油门摇杆调到最低的位置, 然后遥控器通电打开电源开关, 接收机上的LED灯会熄灭, 拔掉接收机上的对码线, 接收机上的灯会常亮此时遥控器和接收已经绑定对好码。
5. 确认你的遥控器是否完全控制绑定对好码的接收机, 再检查每个通道是否正常。
6. 如果对码失败, 请重复整个对码过程。

注意事项: 确保电池给遥控器提供足够的电力。当“滴滴”报警声音和红色电源指示灯闪烁, 请更换遥控器电池。



### 四. 陀螺仪校准:

1. 飞机通电后, 把飞机放在水平地面上静止不动。
2. 快速拨动 (约6秒内) 遥控器左侧角上的 A:D/R 开关 8 次左右, 拨完后把 A:D/R 开关拨停到自稳模式的位置。(A:D/R 开关是校准开关也是自稳模式和手动模式的开关。)
3. 几秒钟后, 飞机的机翼舵面会停止颤动, 舵面会回平到初始位置, 再等待 5 秒飞机自检完。



### 五. 遥控器附带特色:

1. 支持锂电池改装。4.2V~15V 锂电均可使用 (在电池仓直接直插即可)。
2. 遥控器在工作时电流 40mA~60mA 之间, 超长待机, 极度省电。

### 3. Transmitter and receiver match code operate steps:

1. Close transmitter.
2. Plug the black "code line" into the interface of receiver "B", and then plug the signal wire into the third channel port of receiver.
3. Reception will have a continuous flashing LED green light.
4. Put the throttle rocker of the remote control in the lowest position, and then turn on the power of the remote control. The LED light on the receiver will go out, unplug the code line on the receiver, and the light on the receiver will always be on. At this time, the remote control and the receiver have been bound to code.
5. To confirm if your remote control fully controls the receiver that is bound to the correct code, and then double check if each channel is normal.
6. If the code fails, please repeat the entire process.

Note: make sure the battery provides enough power to the remote controller. When the "drops" alarm sound and red power indicator light flashes, replace the remote control battery.

### 4. Gyroscope calibration:

1. After energizing, keep the aircraft still on the ground.
2. Quickly diddle the A: D/R switch on the left corner of the remote control about 8 times/6s. After dialing, turn the A: D/R switch to the Self stabilizing mode position. (Starting with A: D/R is a switch that is Self stabilizing mode and also manual model.)
3. After a few seconds, the rudder of the wing will stop quivering and will return to its initial position. Then wait more 5 seconds, the aircraft self-check is completed.
4. Gyroscope calibration is over.

### 5. Features of remote control:

1. Support lithium battery modification. 4.2V~15V lithium battery can be used (plug directly into the battery compartment).
2. Remote control at the time of operation between 40mA~60mA, long standby, extreme power.

